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Users claiming when they increase the PWM position by $\,$ 0.1, the actual position is increased differently making speed control or AFR control innacurate.

To fix the issue, connect to the actuator through TTL (using RS232 to TTL converter or P/N 8923-1061), use the Service tool and after you establish communication Go to File --> Open control configuration click to the Setup Tab and uncheck the Non Linear box as shown below

